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UG Mechanical 2024-25 PYQP

UG Mech Even sem 2024-25 QP

2025-05-05

MECHATRONICS

Department of Mechanical Engineering – SEAS

SRM UNIVERSITY A.P

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SRM UNIVERSITY – AP, ANDHRA PRADESH

End Term Examination, May 2025

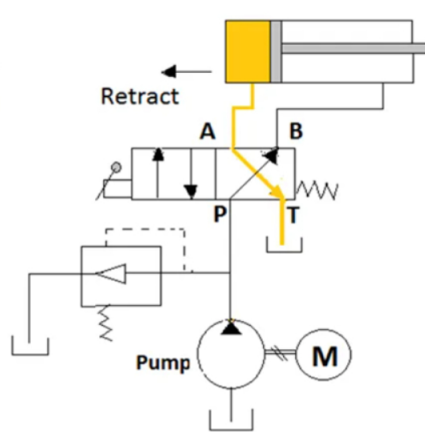
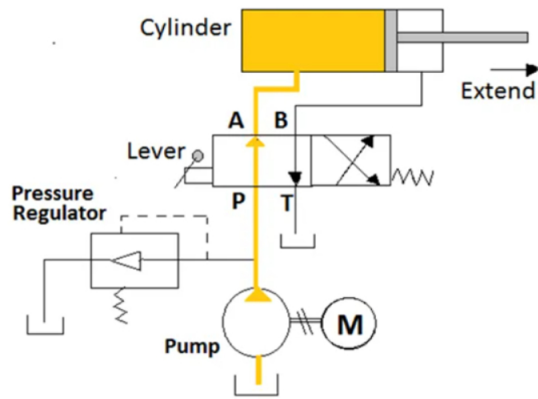
[Question Paper ID: 009144]

Subject : MECHATRONICS
Title
Batch : 2022, 2023
Degree : B.Tech.
Branch : CSE, ECE, EEE

Subject : MCE 242
Code
Max Marks : 100
Duration : 3 hours
QP Set : ---

Section A (5 × 6 Marks = 30 Marks)				Marks BL		CO
Answer all Questions						
1.	1.	Distinguish between open loop and closed loop control system. (3 Marks)	6	6	2	1
	2.	Distinguish between serial communication and parallel communication. (3 Marks)				
2.	Briefly outline the principle of the following: (2 x 3 = 6 Marks)		6	6	2	2
	1.	Strain gauge				
	2.	Thermocouple				
3.	1.	Distinguish between pneumatic and hydraulic systems. (3 Marks)	6	6	2	3
	2.	Briefly outline the principle of solenoid and its use in fluid power systems. (3 Marks)				
4.	1.	Briefly outline the scanning process in a PLC. (3 Marks)	6	6	2	4
	2.	Distinguish between NO and NC. (3 Marks)				
5.	Distinguish between the microprocessor and the microcontroller.		6	6	2	5
Section B (5 × 14 Marks = 70 Marks)				Marks BL		CO
Answer all Questions						
6.	(a)	You are asked to design and fabricate a working model of ANY ONE of the following mechatronic system using a low-cost controller such as Arduino. • Elevator for a six-storey building OR Automatic coffee vending machine Describe all aspects of the design such as from conceptual design, fabrication, parts required including sensors and actuators, controller design and user interface. (OR)	14	14	6	1
	(b)	1. Describe the RS-232 Serial communication protocol, also highlighting the DB-9 and DB-25 connectors. (10 Marks) 2. How are Rs-422 and RS-423 different from RS-232? (4 Marks)				
7.	(a)	1. Describe the principle of an incremental encoder and its application. (6 Marks) 2. Describe ANY TWO sensors used for temperature measurement. (8 Marks) (OR)	14	14	2	2
	(b)	1. Describe the need and the principle of temperature compensation of strain measurement. (7 Marks) 2. Describe the principle of operation of a force-torque sensor. (7 Marks)				
8.						

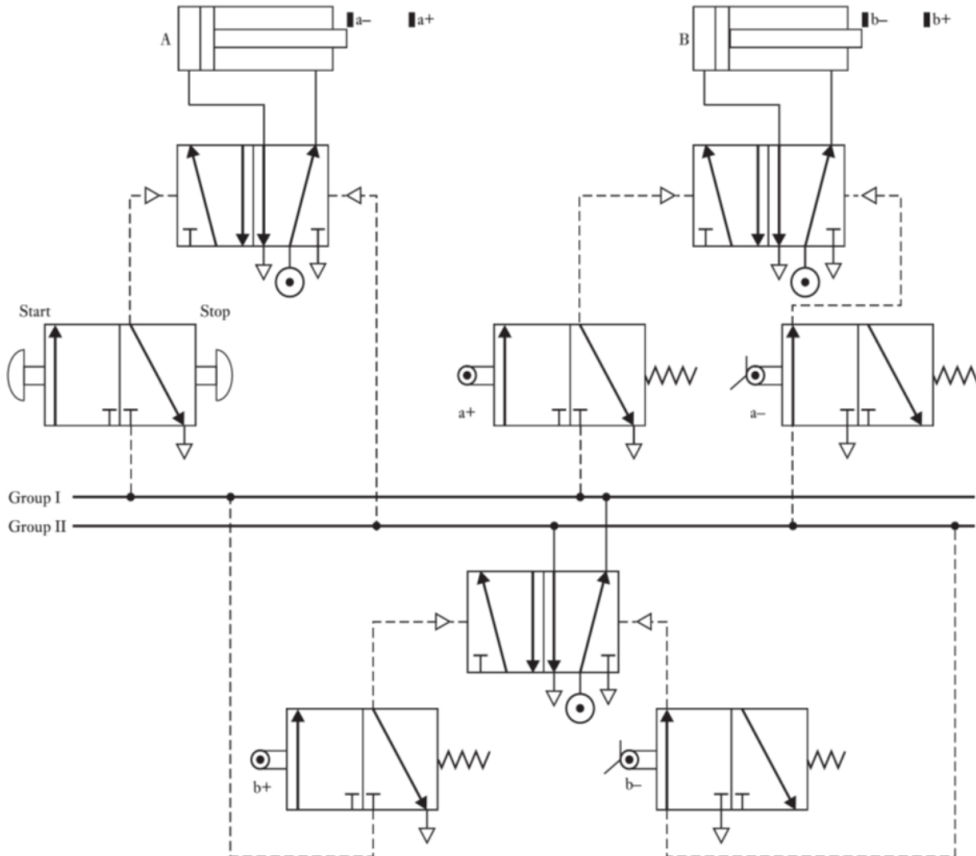
(a)



14 14 4 3

(OR)

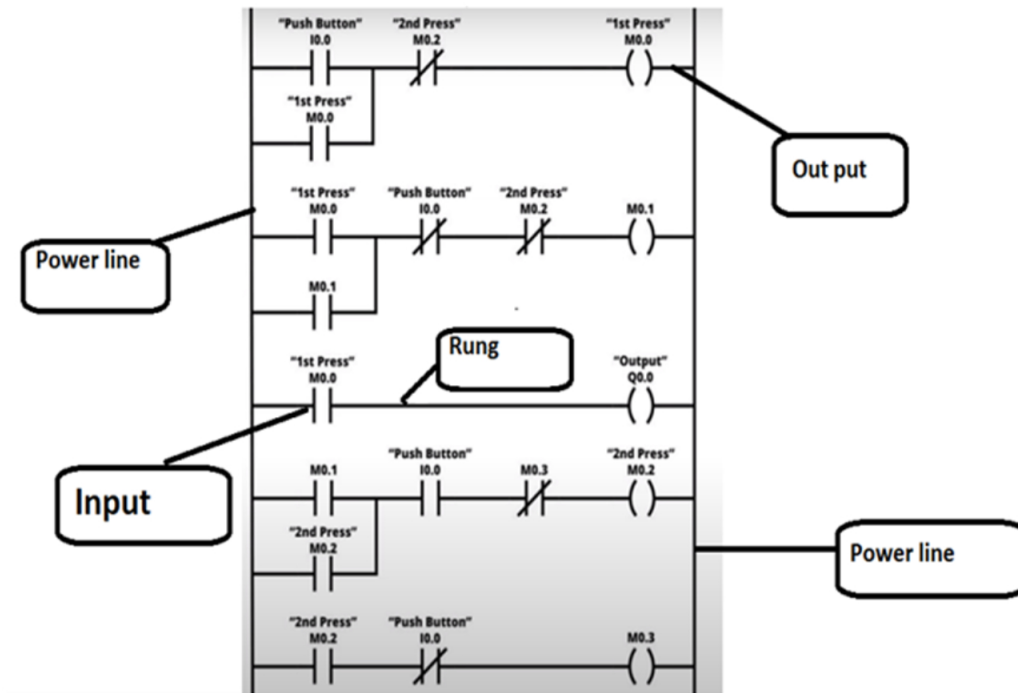
(b)



9. (a) 1. List the five different methods of PLC programming. **(5 Marks)**
 2. Write down the specifications of a typical PLC. **(4 Marks)**
 3. Write the ladder program for the following actions to be executed in the order listed: **(5 Marks)**
 4. Single-push switch (IN001) starts Motor A (CR001)
 5. Single-push switch (IN002) stops Motor A but starts Motor B (CR002)
 6. Motor B turns off automatically after 15 seconds.

(OR)

- (b) 1. Draw the ladder diagram for ANY FOUR Boolean logics. **(6 Marks)**
 2. Briefly describe the functioning of the ladder logic diagram given below: **(8 Marks)**



10. (a) 1. Draw the pin diagram of the 8051 microcontrollers. (7 Marks)
 2. Describe ANY THREE addressing modes of a microprocessor with example. (7 Marks)

14 14 2 5

(OR)

- (b) 1. Distinguish between the program counter and the instruction register. (3 Marks)
 2. Write the 8051 instructions to move the value 34H into Register A, 3FH into Register B, and then add them together. (5 Marks)
 3. Explain the operations specified by each of the following instructions: (6 Marks)
 4. STAB \$35
 5. CMP A # \$CS
 6. LDAA # \$F2

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